

LINFO1131

Concurrent programming concepts

Lectures 2 and 3: Lazy evaluation and declarative programming

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Overview

- Introduction to lazy evaluation
 - Semantics based on dataflow
- Lazy streams
 - Three kinds of producer-consumer
 - Infinite lists
 - Hamming problem
- Lazy suspensions
 - Graphical representation of lazy evaluation
- Lazy deterministic dataflow
 - Bounded buffer
- Lazy quicksort
 - Inventing an incremental algorithm
- What is declarative programming?
 - Partial termination
 - Equivalent stores
 - Definition of declarative programming
 - Failure confinement
- Table of declarative paradigms
- Conclusions



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Introduction to lazy evaluation



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Introduction to lazy evaluation



- A lazy program is a functional program that executes in “by-need” fashion
 - Nothing is computed until it is “needed”
- Here is a simple example:

```
fun lazy {LazyAdd X Y}
  X+Y
end
S={LazyAdd 10 20}
{Browse S}
```
- Nothing is executed until S is needed:
% Displaying the addition S+100 needs S:
{Browse S+100}

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Semantics of lazy evaluation



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Semantics of LazyAdd



- How does LazyAdd work?
 - Semantics of a program is defined by translation into kernel language
 - We will define what “needing a value” means
- We translate into kernel language:

```
proc {LazyAdd X Y R}  
  thread  
    {WaitNeeded R} R=X+Y  
  end  
end
```
- The {WaitNeeded R} waits until another thread needs R to continue
 - More precisely, it waits until another thread does {Wait R}
 - This is part of dataflow execution...

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Dataflow semantics



- To understand WaitNeeded, we first recall how dataflow execution works
 - Given any expression:
S=X+Y
 - This is translated as:
local V **in**
 {Wait X}
 {Wait Y}
 {PrimitiveAdd X Y V}
 {Bind S V}
end
 - This gives a dataflow execution:
 - {Wait X} suspends until X is bound
 - {Bind X V} binds X to V
 - Programmer-accessible operations are defined using Wait, Bind, and a primitive operation:
 - Arithmetic, boolean expressions
 - Case statements
 - Any operation with an input
 - Function call {F X} where F must be bound to a function value
 - Dot operation R.name where R must be bound to a record
- {WaitNeeded X} suspends until another thread does {Wait X}

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Another example



- We use WaitNeeded directly:
declare X **in**
 {WaitNeeded X}
 X=100
- This displays an unbound variable:
 {Browse X}
- This displays 100 twice (!):
 {Browse X+0}

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General translation scheme



- Given any lazy function:
`fun lazy {F X1 ... Xn}
 <expr>
end`
- This is translated into:
`proc {F X1 ... Xn R}
 thread
 {WaitNeeded R} R=<expr>
 end
end`
- This translation gives the **semantics**, not the **implementation**!
 - A compiler is free to optimize it while respecting the semantics

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Three kinds of producer-consumer



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Producer-consumer code



- We give the code of a simple producer-consumer
 - We will show three different ways to run the same code
 - All three ways are declarative and end up with the same result
- Technically we are just taking advantage of the Church-Rosser theorem
 - All reduction orders of a lambda expression give the same result
 - Also called confluence

```
fun {Prod L H}  
  {Delay 1000} % Wait 1000 ms  
  if L>H then nil  
  else L|{Prod L+1 H}  
end  
end
```

```
fun {Cons S Acc}  
  case S of H|T then  
    Acc+H|{Cons T Acc+H}  
  [] nil then nil  
end  
end
```

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Sequential execution



- We generate 10 elements
 - Nothing is displayed until after 10 seconds
 - This is a **batch execution**

```
declare S1 S2 in  
{Browse S1}  
{Browse S2}  
S1={Prod 1 10}  
S2={Cons S1 0}
```

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Concurrent execution



- We execute both calls in their own threads
 - This is running deterministic dataflow (eager)
 - What is the difference with the sequential version?
 - This is an **incremental execution**

```
declare S1 S2 in  
{Browse S1}  
{Browse S2}  
thread S1={Prod 1 10} end  
thread S2={Cons S1 0} end
```

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Lazy execution



```
fun lazy {Prod L H}  
  {Delay 1000}  
  if L>H then nil  
  else L[{Prod L+1 H}]  
  end  
end  
  
fun lazy {Cons S Acc}  
  case S of H|T then  
    Acc+H|[{Cons T Acc+H}]  
  [] nil then nil  
  end  
end
```

- We annotate both functions as “lazy”
- We execute it:

```
declare S1 S2 in  
{Browse S1}  
{Browse S2}  
S1={Prod 1 10}  
S2={Cons S1 0}
```

- What is going on?
 - Why is nothing computed?
 - How do we run this?
 - {Browse S2.2.1} displays the second element of S2, which will activate its computation

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Eager versus lazy streams



- One way to understand the difference between eager and lazy is to see which agent is driving the execution
- In an eager stream, it is the **producer** that determines when elements are sent
 - Termination is decided by the producer
- In a lazy stream, it is the **consumer** that determines when elements are sent
 - Termination is decided by the consumer

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Infinite lists



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Infinite lists

- With lazy evaluation we can compute with infinite loops
 - We can write programs with infinite lists
 - It works because the execution will only generate the elements that are needed
- An infinite list of integers starting with N:
`fun lazy {Ints N} N|{Ints N+1} end`
- Calling `{Ints 1}` displays an unbound variable:
`L={Ints 1} {Browse L}`
- We can force a computation by examining the list L:
`{Browse L.1}`
`{Browse L.2.1}`

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Semantics of infinite lists

- We can see how infinite lists work by translating to kernel language:
`proc {Ints N R}
 thread
 {WaitNeeded R} R=N|{Ints N+1}
 end
end`
- When we need R by doing `{Browse R.1}`, this causes R to be bound to `N|{Ints N+1}`
 - This causes one element of R to be computed
 - The recursive call will immediately suspend again

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Forcing a computation



- We can force the evaluation of N elements of a list by traversing the list:
proc {Touch L N}
 if N==0 **then skip**
 else {Touch L.2 N-1} **end**
end
- This strange procedure does nothing by itself, yet it forces the work to be done:
 {Touch L 10}
 {Touch L 20}

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Hamming problem



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Hamming problem



- Richard Hamming (1915-1998) was an engineer and mathematician who worked at Bell Labs and invented many useful things
 - Hamming codes, Hamming window, Hamming distance, etc.
 - *The Art of Doing Science and Engineering: Learning to Learn*, by Richard Hamming, 1997. **This book is highly recommended!**
- Today we will investigate the Hamming problem, a simple problem in number sequences
 - It is a dynamic problem where we do not know in advance how much needs to be computed → perfect for lazy evaluation!
 - We will use lazy evaluation to design a simple and efficient solution to this problem

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Hamming problem



- Problem statement:
 - Given the set of numbers of the form $2^a 3^b 5^c$ with integers $a, b, c \geq 0$
 - It is asked to compute these numbers in increasing order: 1 | 2 | 3 | ...
- **We do not know in advance** how many numbers of this sequence will be needed
 - The program should let us compute them incrementally until we are satisfied
 - The program should be efficient in time and memory!

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Algorithm idea



$H = 1 \mid 2 \mid 3 \mid \textcolor{red}{X} \mid \dots$

$\left\{ \begin{array}{l} 2H = 2 \mid \textcolor{red}{4} \mid 6 \mid \dots \\ 3H = 3 \mid \textcolor{red}{6} \mid 9 \mid \dots \\ 5H = \textcolor{red}{5} \mid 10 \mid 15 \mid \dots \end{array} \right.$

$\Rightarrow X = \min(4, 6, 5) = 4$

- Idea: The next number X is 2 times, 3 times, or 5 times one of the previous numbers in the sequence
- We need to keep three sequences derived from H, namely 2H, 3H and 5H, and take the least number not yet used
- Numbers 2 and 3 are already taken
- Next number is either 4, 6, or 5
- We take the minimum of these three: the next number is 4

- We can program this with lazy lists

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Hamming program operations



- The algorithm needs two operations
 - Multiply list elements by an integer
 - Merge two ordered lists
- $L2 = \{\text{Times } L1 \ N\}$
 - Each element of L2 is N times the element of L1
- $L = \{\text{Merge } L1 \ L2\}$
 - Assume L1 and L2 are in increasing order
 - L contains elements of L1 and L2 in increasing order

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Hamming program

```
fun lazy {Times S N}
  case S of H|T then
    N*H|{Times T N}
  end
end

fun lazy {Merge S1 S2}
  case S1|S2 of (H1|T1)|(H2|T2) then
    if H1<H2 then H1|{Merge T1 S2}
    elseif H1>H2 then H2|{Merge S1 T2}
    else /* H1==H2 */ H1|{Merge T1 T2}
    end
  end
end
```

- Main expression:
H=1|{Merge
 {Times H 2}
 {Merge {Times H 3}
 {Times H 5}}}
 {Browse H}

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Lazy suspensions

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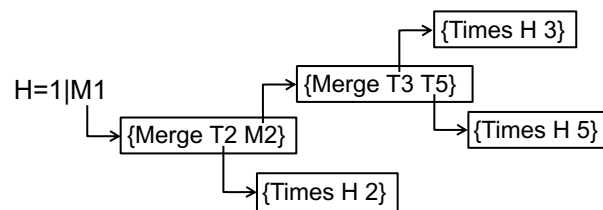
Lazy suspensions



- We defined lazy evaluation using threads and WaitNeeded
 - This is correct but it does not show the execution
- Let us show the execution of a lazy program with a graphical approach
- We introduce the concept of **lazy suspension**:
 Executing: $L2 = \{\text{Times } L1\ 3\}$
 Creates a suspension: $L2 \rightarrow \boxed{\{\text{Times } L1\ 3\}}$
 “A thread is suspended on L2 that contains the body of $\{\text{Times } L1\ 3\}$ ”

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Execution of Hamming program



- Running the program creates **five lazy suspensions**
 - The lazy suspension $\{\text{Merge } T2\ M2\}$ waits on M1
 - Executing M1.1 activates the lazy suspension $\{\text{Merge } T2\ M2\}$, which executes the body of $\{\text{Merge } T2\ M2\}$, which then activates $\{\text{Merge } T3\ T5\}$ and $\{\text{Times } H\ 2\}$, and so forth!
 - All five lazy suspensions are activated and five new ones are created
 - At the end, M1.1 is bound to 2|M1' with the new variable M1'

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First activation: {Merge T2 M2}



- Request the second element of H:
{Browse M1.1}
- This activates {Merge T2 M2}:
 - The body is executed:
`case T2|M2 of (H1|T2') | (H2|M2') then`
 ...
`end`

Activate
{Times H 2}

Activate
{Merge T3 T5}
 - The **case** needs the first elements of T2 and M2
 - This activates {Times H 2} and {Merge T3 T5}
 - The **case** waits patiently until T2 and M2 are bound

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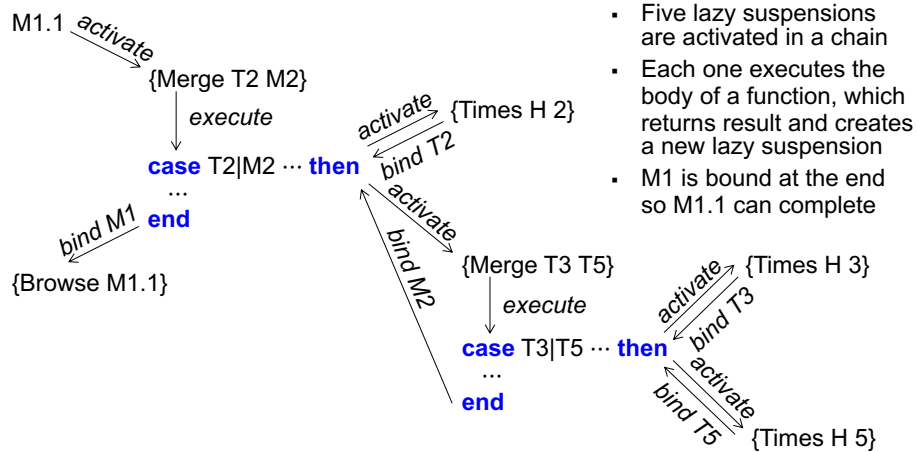
Next activations



- {Times H 2} and {Merge T3 T5} are activated
 - The body of {Times H 2} is executed
 - This binds T2=2|T2' and creates a new lazy suspension on T2':
 {Times M1 2}
 - The body of {Merge T3 T5} is executed
 - This activates {Times H 3} and {Times H 5}
 - After executing these two functions, this binds M2=3|M2' and creates a new lazy suspension on M2': {Merge T3' T5}
- Now the **case** in {Merge T2 M2}, which was waiting patiently, can be executed:
 - It returns 2|M1' with M1'={Merge T2' M2} and creates a new lazy suspension on M1'

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Overall execution flow



- Doing M1.1 starts it all
- Five lazy suspensions are activated in a chain
- Each one executes the body of a function, which returns result and creates a new lazy suspension
- M1 is bound at the end so M1.1 can complete

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Lazy deterministic dataflow



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Five functional paradigms



- So far we have shown four paradigms of functional programming:
 - Sequential functional programming
 - Sequential functional programming with single assignment
 - Allows data structures with “holes”, e.g., list functions are tail-recursive
 - Deterministic dataflow
 - Adds threads and dataflow synchronization
 - Allows concurrent programming with streams
 - Lazy evaluation
 - Adds by-need evaluation (with WaitNeeded), where functions are executed only when their results are needed
 - Allows programming with infinite lists
- There is a fifth paradigm:
 - Lazy deterministic dataflow
 - Adds both threads and lazy functions

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Lazy deterministic dataflow



- Lazy deterministic dataflow is the most powerful declarative paradigm:
 - It has the strong properties of functional programming: **confluence** and **higher-order**
 - It has concurrency: **independent activities** which can get out of step with each other
 - It has lazy evaluation: **by-need computations** which are only done when their result is needed
- What can we do with all this power?
 - We give one example of a program that can be written in lazy deterministic dataflow, but not in any weaker paradigm

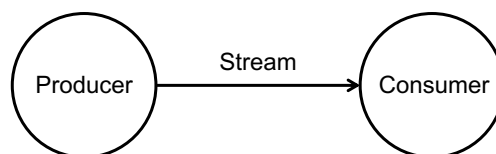
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Bounded buffer



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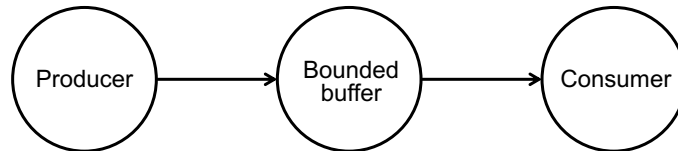
Bounded buffer (1)



- A producer-consumer pipeline has performance problems
 - Variations in producer and consumer speeds can cause the system to perform poorly
 - When a producer creates elements too quickly, the consumer cannot use the elements so the producer idles
 - When a consumer needs more elements, the producer may not be able to produce them so the consumer idles

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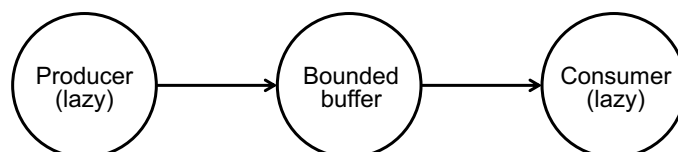
Bounded buffer (2)



- Inserting a bounded buffer can solve these problems
 - When the producer creates elements too quickly to be consumed, they are stored in the bounded buffer
 - When the consumer needs more elements than can be produced, they are taken from the bounded buffer
 - This improves performance by smoothing out fluctuations in producer and consumer speeds

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Bounded buffer (3)



- A bounded buffer fits in between a lazy producer and a lazy consumer
- The code of the producer and consumer is unchanged
 - To the producer, the bounded buffer looks like a consumer
 - To the consumer, the bounded buffer looks like a producer
- The bounded buffer “consumes” elements even when the consumer does not ask for them, and “produces” elements even when the producer does not make them

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Defining the bounded buffer



- Assume we have a producer-consumer pipeline:
`thread S={Producer ...} end`
`thread {Consumer S} end`
- The bounded buffer is inserted in between:
`thread S1={Producer ...} end`
`thread {BoundedBuffer S1 S2 10} end`
`thread {Consumer S2} end`
- We define the bounded buffer step-by-step
 - We define the procedure {BoundedBuffer S1 S2 N} where S1 is the input stream, S2 is the output stream, and N is the buffer size
 - We build the procedure in four steps, to make it easier to understand

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First step: pass elements



- The buffer outputs the same elements as it inputs:

```
proc {BoundedBuffer S1 S2 N}
  fun lazy {Loop S1}
    case S1 of H1|T1 then H1|{Loop T1} end
  end
in
  S2={Loop S1}
end
```

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Second step: startup

- The buffer asks for N elements on startup:

```
proc {BoundedBuffer S1 S2 N}
  fun lazy {Loop S1}
    case S1 of H1|T1 then H1|{Loop T1} end
  end
  End
in
  End={List.drop S1 N} % Asking must not be lazy!
  S2={Loop S1}
end
```

- {List.drop L N} is a library function that removes the first N elements from a list L

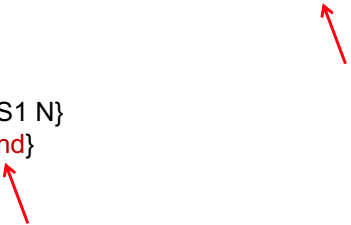
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Third step: staying full

- Whenever the consumer gets an element, the buffer asks for another element from the producer:

```
proc {BoundedBuffer S1 S2 N}
  fun lazy {Loop S1 End}
    case S1 of H1|T1 then H1|{Loop T1 End.2} end
  end
  End
in
  End={List.drop S1 N}
  S2={Loop S1 End}
end
```



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Fourth step: no blocking



- To avoid blocking the buffer's main loop, both asks must be done in their own threads:

```
proc {BoundedBuffer S1 S2 N}
  fun lazy {Loop S1 End}
  case S1 of H1|T1 then
    H1|{Loop T1 thread End.2 end}
  end
end
End
in
  thread End={List.drop S1 N} end
  S2={Loop S1 End}
end
```

In declarative programming, threads are your friends! They are efficient. They can be added at will without adding bugs. They remove blocking and make the program more incremental.

← All list functions, including List.drop, work correctly when used concurrently

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Example execution



- We create a pipeline with producer, bounded buffer, and consumer:

```
declare S1 S2 S3 in
  {Browse S1}
  {Browse S2}
  {Browse S3}
  S1={Prod 1 10}
  {BoundedBuffer S1 S2 3}
  S3={Cons S2 0}
```

- Note that the producer immediately produces 3 elements, which are stored in the buffer
- When we consume one element, the buffer asks the producer for one element
 - The buffer tries to stay full
- The buffer is eager until it is full, and then it becomes lazy

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Lazy quicksort



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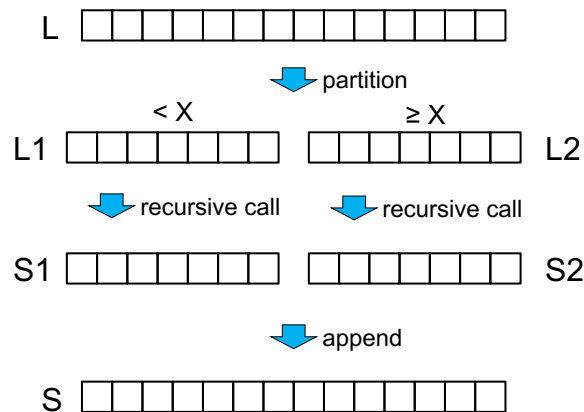
Lazy quicksort



- Lazy evaluation can make some algorithms incremental, which can enormously improve their efficiency
 - We show this with the quicksort algorithm
- Standard quicksort has an average time complexity of $O(n \log n)$ to sort n elements
- Lazy quicksort has a time complexity of $O(n + k \log k)$ to compute the k smallest elements out of n elements
 - This is a very good bound!
 - Furthermore, **the value of k does not need to be known in advance.** Elements can be computed incrementally until some condition is satisfied.
 - To see how clever this is, **try inventing the algorithm from scratch!**

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Quicksort algorithm



- Pick a random element of **L**, the "pivot" **X**
- Partition into two sublists
- Recursively sort the sublists
- Append the results

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Quicksort example (on board)



- **L** = [7 3 2 8 6 4 1 9]
- Pivot = 7 (first element of **L**)
- **L1** = [3 2 6 4 1], **L2** = [7 8 9]
- ...
- **S1** = [1 2 3 4 6], **S2** = [7 8 9]
- **S** = [1 2 3 4 6 7 8 9]

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Partition procedure

```
proc {Partition L X L1 L2}
  case L of H|T then
    if H<X then M1 in
      L1=H|M1 {Partition T X M1 L2}
    else /* H≥X */ M2 in
      L2=H|M2 {Partition T X L1 M2}
    end
  [] nil then L1=nil L2=nil
  end
end
```

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Append and quicksort

```
fun {Append L1 L2}
  case L1 of H|T then H|{Append T L2}
  [] nil then L2 end
end
fun {Quicksort L}
  case L of X|M then L1 L2 S1 S2 in
    {Partition L X L1 L2}
    S1={Quicksort L1}
    S2={Quicksort L2}
    {Append S1 S2}
  [] nil then nil
  end
end
```

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Example eager execution

- Let us try to run this:
declare S in
S={Quicksort [4 3 2 5 6 4 3 2]}
{Browse S}
- What happens?
 - Something is wrong!
- How do we fix this?
 - A general rule when defining recursive functions!

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Append and quicksort (fixed)

```
fun {Append L1 L2}
  case L1 of H|T then H|{Append T L2}
  [] nil then L2 end
end
fun {Quicksort L}
  case L of X|M then L1 L2 S1 S2 in
    {Partition M X L1 L2}
    S1={Quicksort L1} % L1 is strictly smaller than L
    S2={Quicksort L2} % L2 is strictly smaller than L
    {Append S1 X|S2}
  [] nil then nil
  end
end
```

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Making quicksort lazy

- What has to be made lazy?
 - Quicksort function becomes LQuicksort
 - Append function becomes LAppend
- Partition is **not lazy**
 - Sorting cannot work unless we look at all the elements of L
 - Partition keeps the same eager definition
 - We create the complete sublists L1 and L2

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Lazy append and quicksort

```
fun lazy {LAppend L1 L2}
  case L1 of H|T then H|{LAppend T L2}
  [] nil then L2 end
end
fun lazy {LQuicksort L}
  case L of X|M then L1 L2 S1 S2 in
    {Partition M X L1 L2}
    S1={LQuicksort L1}
    S2={LQuicksort L2}
    {LAppend S1 X|S2}
  [] nil then nil
  end
end
```

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Example lazy executions



- Lazy append:
declare S in
 S={LAppend [1 2 3] [4 5 6]}
 {Browse S}
 - What happens when asking for elements?
- Lazy quicksort:
declare S in
 S={LQuicksort [4 3 2 5 6 4 3 2]}
 {Browse S}
 - What happens when asking for the first element?
 - How much computation is done? What is the time complexity?

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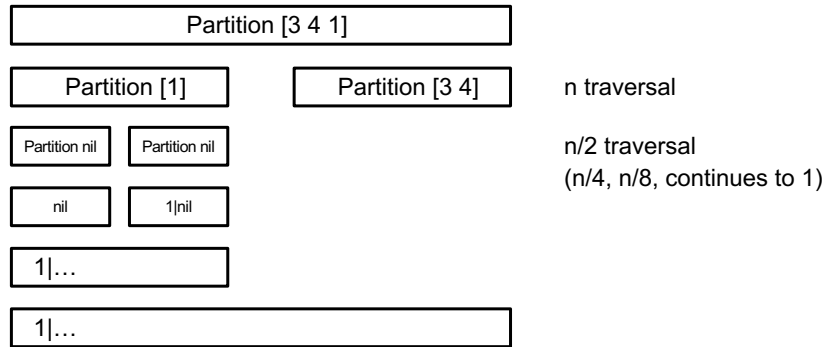
Execution steps...



- S={LQuicksort [2 3 4 1]} % Lazy suspension on S
 {Browse S.1}
 % S is needed, so execute body of S={LQuicksort [2 3 4 1]}:
 {Partition [3 4 1] 2 L1 L2}
 S1={LQuicksort [1]} % Lazy suspension on S1
 S2={LQuicksort [3 4]} % Lazy suspension on S2
 S={LAppend S1 2|S2} % Lazy suspension on S
 % S still needed, so execute body of LAppend:
 case S1 of H|T then H|{LAppend T 2|S2}
 [] nil then 2|S2 end
 % S1 is needed, so execute body of S1={LQuicksort [1]}
 {Partition nil 1 nil nil}
 S1'={LQuicksort nil} % Lazy suspension on S1'
 S2'={LQuicksort nil} % Lazy suspension on S2'
 S1={LAppend S1' 1|S2'} % Lazy suspension on S1
 % S1 still needed, so execute body of LAppend:
 case S1' of H|T then H|{LAppend T' 1|S2'}
 [] nil then 1|S2' end
 % S1' is needed, so execute body of S1'={LQuicksort nil}:
 case nil of X|M' then (...)
 [] nil then nil end
 % Now we can do bindings:
 S1'=nil
 S1=1|S2'
 S=1|{LAppend nil 2|S2}
 {Browse (1...)1}
 % Displays 1
- Follow carefully what is happening
 - When S is needed, it stays needed!
 - We focus on the lazy suspensions
- S → {LQuicksort [2 3 4 1]}
 S is needed, activates:
 - S1 → {LQuicksort [1]}
 - S2 → {LQuicksort [3 4]}
 - S → {LAppend S1 2|S2}
 S still needed, activates:
 S1 is needed, activates:
 - S1' → {LQuicksort nil}
 - S2' → {LQuicksort nil}
 - S1 → {LAppend S1' 1|S2}
 S1 still needed, activates:
 S1' is needed, activates:
 - S1'=nil
 - S1=1|S2'
- S=1|{LAppend nil 2|S2}

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Complexity of lazy quicksort



- To compute the smallest element, the number of operations is $n + n/2 + n/4 + \dots + 1 = 2n$, so the **time complexity is $O(n)$**
- To compute the k smallest elements, a full "mini quicksort" is done as soon as the partitioned list has at least k elements, so the **extra time complexity is $O(k \log k)$**
- **Total time complexity is $O(n + k \log k)$**

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What is declarative programming?



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Declarative programming



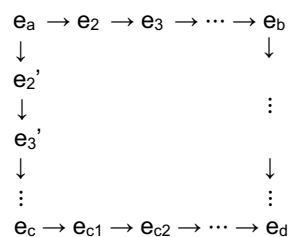
- We have seen **five functional paradigms**
 - Sequential functional programming
 - Sequential functional programming with single assignment
 - Deterministic dataflow
 - Lazy evaluation
 - Lazy deterministic dataflow
- We claim that they are **all declarative**
 - What does this mean, exactly?
 - Let us define it starting from the functional programming paradigm
- We show how to classify declarative paradigms according to their concepts and expressive power (Section 4.5.2 in the book)

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Functional programming



- All functional programs can be encoded as λ expressions
- Church-Rosser theorem:



- If e_a reduces to e_b (in 0 or more steps) and e_a reduces to e_c (in 0 or more steps), then there exists a term e_d such that e_b and e_c can reduce to e_d
- We say the λ calculus is **confluent**; it has the **Church-Rosser property**

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Other functional paradigms?



- We see that functional programs are confluent
 - The meaning is clear for the first paradigm, namely sequential functional programming
- But what does it mean for:
 - **Concurrency?**
 - **Streams?** (programs never terminate!)
 - **Single-assignment variables?** (variables can be unbound!)
- We give a precise formal definition of “declarative programming” which covers these concepts
 - **Confluence:** this handles concurrency (why?)
 - **Partial termination**
 - **Equivalent stores**

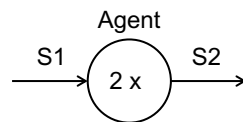
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I: Partial termination



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Partial termination



- Assume we have a concurrent agent with an input stream S1 and an output stream S2
- It could execute as follows:
 - S1=1|_ S2=2|_
 - S1=1|2|_ S2=2|4|_
 - S1=1|2|3|_ S2=2|4|6|_
- How is this functional?
 - The program never terminates and the streams contain unbound variables
- With the right concepts, we can see this as functional execution:
 - If S1 does not change, then S2 reaches a final value
 - We call this "partial termination"
 - We say the program has reached a "resting point"
- What about the unbound variables?

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II: Equivalent stores

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Single-assignment variables



- We claim that a functional program that uses single-assignment variables is still functional
 - Let's see how to make this precise
- Consider the following program:
T₁: **thread** X=foo(Z W) **end**
T₂: **thread** Y=foo(Z W) **end**
T₃: **thread** X=Y **end**
 - Assume T₁ and T₂ execute before T₃, then we have the store:
 $\sigma = \{x = \text{foo}(z\ w), y = \text{foo}(z\ w)\}$
 - Assume T₁ and T₃ execute before T₂, then we have the store:
 $\sigma' = \{x = \text{foo}(z\ w), y = x\}$
- How can we express that stores σ and σ' are the same?

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A store is a logical formula



- Assume we have these two stores:
 $\sigma = \{x = \text{foo}(z\ w), y = \text{foo}(z\ w)\}$
 $\sigma' = \{x = \text{foo}(z\ w), y = x\}$
- The bindings of x and y are different for σ and σ' but the possible values of x and y are the same in both stores
 - Let's see how to make this intuition precise
- A store σ corresponds to a **relationship between values**
 - The store σ tells us that x is a record with label `foo` and arguments z and w , and that y is a record with label `foo` and arguments z and w
 - For any values of x , y , z , and w , there are two possibilities: either they can be in the store σ or they cannot be in the store σ
 - So the store σ is a **logical formula**, which can be true or false
 - We write σ as a logical formula: $\sigma \equiv x = \text{foo}(z\ w) \wedge y = \text{foo}(z\ w)$

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Interpretation and model



- Definition: An **interpretation** of a store σ
 - An **interpretation** of a store σ is an assignment to all symbols in σ
 - For all variables x in σ , assign a value \mathbf{x} to x
 - For all record symbols f in σ , assign a function \mathbf{f} to f that has the same number of arguments as the record symbol and that returns a value
 - Any interpretation of a store σ is either **true** or **false**
 - A binding $x=f(x_1 \dots x_n)$ is **true** if the value returned by $\mathbf{f}(\mathbf{x}_1 \dots \mathbf{x}_n)$ is equal to \mathbf{x} ; otherwise it is **false**
 - A store $\sigma = (x=f(x_1 \dots x_n) \wedge \dots \wedge z=f(z_1 \dots z_n))$ is **true** if all bindings are **true**, otherwise it is **false**
- Definition: A **model** of a store σ
 - A model of σ is an interpretation in which σ is **true**

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Equivalent stores



- Now we can define when two stores are equivalent
 - Each store represents a logical formula that can be **true** or **false**
 - Two stores are equivalent when, no matter how we assign values to their symbols, they are either **both true** or **both false**
 - I.e., we cannot find values such that one store is **true** and the other is **false**
- We state this definition using the model concept
 - We introduce the notation $\alpha=\beta$ which means “ β is true in all models of α ”
- Definition: Two stores σ and σ' are **logically equivalent** if
 - $\sigma=\sigma'$ and $\sigma'=\sigma$ σ' is **true** in all models of σ and σ is **true** in all models of σ'
- Another way to write this is:
 - $\models (\sigma \Leftrightarrow \sigma')$ $(\sigma \Leftrightarrow \sigma')$ is a tautology, i.e., it is **true** in all models

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First-order logic



- To define equivalence of stores, we have introduced a little bit of **first-order logic**
 - **Logical formula** (syntax)
 - An expression that denotes a relationship between variables
 - **Model** (semantics)
 - A set of values and functions in which logical formulas are true or false
- If you want to understand more, you need to study first-order logic!
 - There are programming languages that are based on first-order logic, such as **Prolog**, **constraint programming**, and **SQL**

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III: Definition of declarative programming



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Definition of declarative programming



- Now we can define precisely what declarative programming means

A program is **declarative** if for all possible inputs:

- All executions for those inputs either:
 - do not terminate, or
 - all reach **partial termination** and give **logically equivalent** stores

- Remarks:
 - “All executions” means all possible choices of the scheduler
 - We say that a declarative program has “no observable nondeterminism”
 - All five functional paradigms are declarative

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IV: Failure confinement



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Fixing a buggy application



- Declarativeness is an extremely powerful property
 - How do we write applications to be as declarative as possible?
 - This is a major theme of the course! “All programs should be declarative except where they interact with the real world.”
 - How do we fix an application that becomes nondeclarative?
 - We can do **failure confinement**
- Nondeclarative behavior
 - We will see later in the course that applications that interact with the real world can be nondeclarative
 - That kind of nondeclarativeness is unavoidable but can be minimized
 - Right now, let us see what happens when an application has a **bug** that makes it nondeclarative

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Bugs are unavoidable



- “It is a truth universally acknowledged, that a program of a certain size must have bugs”
 - With apologies to Jane Austen 😊
- Assume we have the following (simplified!) buggy program:
thread X=1 **end**
thread Y=2 **end**
thread X=Y **end**
- This program will **always raise an exception**
 - Three stores are possible depending on the scheduler choices:
 $\sigma_1=\{x=1, y=2\}$, $\sigma_2=\{x=1, y=1\}$, $\sigma_3=\{x=2, y=2\}$
 - This is **an observable nondeterminism**, so it is nondeclarative
- We can fix this by doing failure confinement
 - We will hide the nondeterminism from the rest of the program
 - That way the program becomes declarative again

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Failure confinement



- The program has three parts that can become inconsistent if there is a bug
 - We use exceptions to protect these parts

```
thread try X1=1 S1=ok catch _ then S1=error end end
thread try Y1=2 S2=ok catch _ then S2=error end end
thread try X1=Y1 S3=ok catch _ then S3=error end end
if S1==error orelse S2==error orelse S3==error then
  X=1 Y=1 /* default result when there is an error */
else
  X=X1 Y=Y1 /* correct result when there is no error */
end
```

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Table of declarative paradigms



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Declarative paradigms



	<i>sequential with values</i>	<i>sequential with values and dataflow variables</i>	<i>concurrent with values and dataflow variables</i>
<i>eager execution (strictness)</i>	strict functional programming (e.g., Scheme, ML) (1)&(2)&(3)	declarative model (e.g., Chapter 2, Prolog) (1), (2)&(3)	data-driven concurrent model (e.g., Section 4.1) (1), (2)&(3)
<i>lazy execution</i>	lazy functional programming (e.g., Haskell) (1)&(2), (3)	lazy FP with dataflow variables (1), (2), (3)	demand-driven concurrent model (e.g., Section 4.5.1) (1), (2), (3)

- (1): Declare a variable in the store
 (2): Specify the function to calculate the variable's value
 (3): Evaluate the function and bind the variable
 (1)&(2)&(3): Declaring, specifying, and evaluating all coincide
 (1)&(2), (3): Declaring and specifying coincide; evaluating is done later
 (1), (2)&(3): Declaring is done first; specifying and evaluating are done later and coincide
 (1), (2), (3): Declaring, specifying, and evaluating are done separately

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Conclusions



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Conclusions

- Lazy evaluation
 - Functions are evaluated only **if their results are needed**
 - This extends deterministic dataflow with the WaitNeeded operation
 - Programs can use infinite lists and be made more incremental
 - Lazy evaluation can be combined with concurrency
- Declarative programming
 - An application should be declarative except for real-world interaction
 - We need to define precisely **what is declarative programming**
 - We give a precise definition of declarative programming using the concepts of **confluence**, **partial termination**, and **logical equivalence**
 - Declarativeness is an **observational concept**: a program can behave declaratively even if it is written in a nondeclarative paradigm
- Next lecture: Advanced declarative algorithm design
 - Declarative algorithms can be as efficient as nondeclarative algorithms